TẠP CHÍ KHOA HỌC & CÔNG NGHỆ ĐẠI HỌC DUY TÂNDTU Journal of Science and Technology5(48) (2021) 121-125



Strong two-scale convergence for a two-dimensional case

Hội tụ hai-kích thước mạnh cho một trường hợp hai chiều

Tina Mai^{*a,b,**} Mai Ti Na^{*a,b,**}

^aInstitute of Research and Development, Duy Tan University, Da Nang, 550000, Vietnam ^bFaculty of Natural Sciences, Duy Tan University, Da Nang, 550000, Vietnam

^aViện Nghiên cứu và Phát triển Công nghệ Cao, Trường Đại học Duy Tân, Đà Nẵng, Việt Nam
^bKhoa Khoa học Tự nhiên, Trường Đại học Duy Tân, Đà Nẵng, Việt Nam

(Ngày nhận bài: 16/06/2021, ngày phản biện xong: 19/06/2021, ngày chấp nhận đăng: 20/10/2021)

Abstract

In this paper, we present definitions and some properties of the classical strong two-scale convergence for component-wise vector or matrix functions in a two-dimensional case.

Keywords: two-scale homogenization; strong two-scale convergence; two-dimensional

Tóm tắt

Trong bài báo này, chúng tôi trình bày các định nghĩa và một số tính chất của hội tụ hai-kích thước mạnh cổ điển cho các hàm vecto hoặc ma trận trong một trường hợp hai chiều.

Từ khóa: đồng nhất hóa hai-kích thước; hội tụ hai-kích thước mạnh; hai chiều

1. Introduction

We are given in dimension two, a bounded reference domain $\Omega = \Omega^1 \times \Omega^2 \in \mathbb{R} \times \mathbb{R}$ and a variable $\mathbf{x} = (x^1, x^2) \in \Omega$. In two-scale homogenization theory, strong two-scale convergence can be viewed as an intermediate property between the usual (one-scale) weak and strong convergence.

In light of this spirit, we first give a neccesary review of the usual weak convergence in the Hilbert space $L^2(\Omega)$ then the definitions and properties of the classical strong two-scale convergence for component-wise vector or matrix functions [1, 2], in a two-dimensional case.

2. Preliminaries

Latin indices are in the set {1,2}. The space of functions, vector fields in \mathbb{R}^2 , and 2×2 matrix fields, defined over Ω are represented respectively by italic capitals (e.g. $L^2(\Omega)$), boldface Roman capitals (e.g. V), and special Roman capitals (e.g. \mathbb{S}).

In the rest of this paper, we use the following notations [1]:

^{*} Corresponding Author: Tina Mai; Institute of Research and Development, Duy Tan University, Da Nang, 550000, Vietnam; Faculty of Natural Sciences, Duy Tan University, Da Nang, 550000, Vietnam; Email: maitina@duytan.edu.vn

- $Y := [0, 1]^2$ is the reference periodic cell.
- **C**₀(Ω) is the space of functions that vanish at infinity.
- C[∞]_{per}(Y) denotes the Y-periodic C[∞] vectorvalued functions in ℝ². Here, Y-periodic means 1-periodic in each variable yⁱ, i = 1,2.
- The notation H¹_{per}(Y), as the closure for the H¹-norm of C[∞]_{per}(Y), is the space of vector-valued functions v ∈ L²(Y) such that v(y) is Y-periodic in ℝ².

$$\langle \boldsymbol{v} \rangle_{\boldsymbol{y}} = \frac{1}{|\boldsymbol{Y}|} \int_{\boldsymbol{Y}} \boldsymbol{v}(\boldsymbol{y}) \, \mathrm{d} \boldsymbol{y}.$$

$$\boldsymbol{H}_{\text{per}}(Y) := \{ \boldsymbol{v} \in \boldsymbol{H}_{\text{per}}^{1}(Y) \mid \langle \boldsymbol{v} \rangle_{Y} = 0 \}.$$

- We use · for the canonical inner products in ℝ² and ℝ^{2×2}, respectively.
- The notation ≤ stands for ≤ up to a multiplicative constant that only depends on Ω when applicable.

The Sobolev norm $\|\cdot\|_{W^{1,2}_{0}(\Omega)}$ has the form

$$\|\boldsymbol{\nu}\|_{\boldsymbol{W}_{0}^{1,2}(\Omega)} = (\|\boldsymbol{\nu}\|_{\boldsymbol{L}^{2}(\Omega)}^{2} + \|\nabla\boldsymbol{\nu}\|_{\mathbb{L}^{2}(\Omega)}^{2})^{\frac{1}{2}};$$

here, $\|\boldsymbol{v}\|_{\boldsymbol{L}^{2}(\Omega)} := \||\boldsymbol{v}\|\|_{\boldsymbol{L}^{2}(\Omega)}$, where $|\boldsymbol{v}|$ represents the Euclidean norm of the 2-component vectorvalued function \boldsymbol{v} , and $\|\nabla \boldsymbol{v}\|_{\mathbb{L}^{2}(\Omega)} := \||\nabla \boldsymbol{v}\|\|_{\mathbb{L}^{2}(\Omega)}$, where $|\nabla \boldsymbol{v}|$ denotes the Frobenius norm of the 2×2 matrix $\nabla \boldsymbol{v}$. Recall that the Frobenius norm on $\mathbb{L}^{2}(\Omega)$ is specified by $|\boldsymbol{X}|^{2} := \boldsymbol{X} \cdot \boldsymbol{X} = \operatorname{tr}(\boldsymbol{X}^{T}\boldsymbol{X})$.

Let ϵ be some natural small scale. For potential applications in homogenization, based on [3, 4, 5, 6], we consider $u_{\epsilon}(x) \in W_0^{1,2}(\Omega)$ depending on x^1 only, that is, $u_{\epsilon}(x) = u_{\epsilon}(x^1)$, with boundary conditions of Neumann type. As remarked in [7], we do not distinguish between a function on \mathbb{R} and its extension to \mathbb{R}^2 as a function of the first variable. It is assumed that $u_{\epsilon}(x^1) = u\left(\frac{x^1}{\epsilon}\right)$ is a periodic function in x^1 with

period ϵ , equivalently, $u\left(\frac{x^1}{\epsilon}\right) = u(y^1)$ is a periodic function in y^1 with period 1. That is, for any integer k,

$$\boldsymbol{u}_{\epsilon}(x^{1}) = \boldsymbol{u}_{\epsilon}(x^{1} + \epsilon) = \boldsymbol{u}_{\epsilon}(x^{1} + k\epsilon)$$

equivalently,

$$\boldsymbol{u}\left(\frac{x^1}{\epsilon}\right) = \boldsymbol{u}\left(\frac{x^1}{\epsilon}+1\right) = \boldsymbol{u}\left(\frac{x^1}{\epsilon}+k1\right) = \boldsymbol{u}(y^1+k).$$

3. Weak convergence

In the Hilbert space $L^2(\Omega)$, we describe the basic notions of the usual weak convergence, which is defined below [8].

Consider a sequence of functions $u_{\epsilon} \in L^{2}(\Omega)$. Then, (u_{ϵ}) is said to be bounded in $L^{2}(\Omega)$ if

$$\limsup_{\epsilon \to 0} \int_{\Omega} |\boldsymbol{u}_{\epsilon}|^2 \, \mathrm{d} x \le c < \infty,$$

for some positive constant *c*.

By definition, a sequence $(u_{\epsilon}(x)) \in L^{2}(\Omega)$ is weakly convergent to $u(x) \in L^{2}(\Omega)$ as $\epsilon \to 0$, denoted by $u_{\epsilon} \to u$, if

$$\lim_{\varepsilon \to 0} \int_{\Omega} \boldsymbol{u}_{\varepsilon}(\boldsymbol{x}) \cdot \boldsymbol{\phi} \, \mathrm{d}\boldsymbol{x} = \int_{\Omega} \boldsymbol{u} \cdot \boldsymbol{\phi} \, \mathrm{d}\boldsymbol{x}, \qquad (1)$$

for any test function $\phi \in L^2(\Omega)$.

Furthermore, a sequence (u_{ϵ}) in $L^{2}(\Omega)$ is called strongly convergent to $u \in L^{2}(\Omega)$ as $\epsilon \to 0$, denoted by $u_{\epsilon} \to u$, if

$$\lim_{\varepsilon \to 0} \int_{\Omega} \boldsymbol{u}_{\varepsilon} \cdot \boldsymbol{v}_{\varepsilon} \, \mathrm{d}x = \int_{\Omega} \boldsymbol{u} \cdot \boldsymbol{v} \, \mathrm{d}x, \qquad (2)$$

for every sequence $(\boldsymbol{v}_{\epsilon}) \in \boldsymbol{L}^{2}(\Omega)$ which is weakly convergent to $\boldsymbol{v} \in \boldsymbol{L}^{2}(\Omega)$.

The following are well-known weak convergence properties in $L^2(\Omega)$.

- (a) Any weakly convergent sequence is bounded in $L^2(\Omega)$.
- (b) Compactness principle: any bounded sequence in $L^2(\Omega)$ has a weakly convergent subsequence.
- (c) If a sequence (u_{ε}) is bounded in $L^{2}(\Omega)$ and (1) is satisfied for all $\phi \in C_{0}^{\infty}(\Omega)$, then $u_{\varepsilon} \rightarrow u \in L^{2}(\Omega)$.

(d) If $u_{\epsilon} \rightarrow u \in L^{2}(\Omega)$ and $v_{\epsilon} \rightarrow v \in L^{2}(\Omega)$, then

$$\lim_{\epsilon \to 0} \int_{\Omega} \boldsymbol{u}_{\epsilon} \cdot \boldsymbol{v}_{\epsilon} \, \mathrm{d} \boldsymbol{x} = \int_{\Omega} \boldsymbol{u} \cdot \boldsymbol{v} \, \mathrm{d} \boldsymbol{x}.$$

(e) Weak convergence of $(\boldsymbol{u}_{\epsilon})$ to \boldsymbol{u} in $L^{2}(\Omega)$ together with

$$\lim_{\epsilon \to 0} \int_{\Omega} |\boldsymbol{u}_{\epsilon}|^2 \, \mathrm{d}x = \int_{\Omega} |\boldsymbol{u}|^2 \, \mathrm{d}x$$

is equivalent to strong convergence of (u_{ϵ}) to u in $L^{2}(\Omega)$.

Hereafter, we denote by $Y = [0, 1]^2$ the cell of periodicity. (In our paper, a periodic cell has the form $Y = [0, 1] \times [0, 1]$.) The mean value of a 1-periodic function $\boldsymbol{\psi}(y^1)$ is denoted by $\langle \boldsymbol{\psi} \rangle$, that is,

$$\langle \boldsymbol{\psi} \rangle \equiv \int_{Y^1} \boldsymbol{\psi}(y^1) \,\mathrm{d}y^1$$

Recall that $y^1 = e^{-1}x^1$, and we do not distinguish between a function on Y^1 and its extension to Yas a function of the first variable only.

Also, in our paper, the symbol $L^2(Y)$ is used not only for functions defined on Y but also for the space of functions in $L^2(Y)$ extended by 1-periodicity to all \mathbb{R}^2 . Similarly, $C_{per}^{\infty}(Y)$ represents the space of infinitely differentiable 1periodic functions on the entire \mathbb{R}^2 .

For later use, we need the following classical result.

Lemma 3.1 (The mean value property). Let $h(y^1)$ be a 1-periodic function on \mathbb{R} and $h \in L^2(Y^1)$. Then, for any bounded domain Ω , there holds the weak convergence

$$h\left(\frac{x^1}{\epsilon}\right) \rightarrow \langle h \rangle \ in \ L^2(\Omega) \ as \ \epsilon \rightarrow 0.$$
 (3)

Proof. The proof is based on property (c) and can be found in [8].

4. Weak two-scale convergence

We have the following definition of weak two-scale convergence in $L^2(\Omega)$ (introduced by in 1989 by Nguetseng) [1, 2]. **Definition 4.1.** Let (u_{ϵ}) be a bounded sequence in $L^{2}(\Omega)$. If there exist a subsequence, still denoted by u_{ϵ} , and a function $u(\mathbf{x}, y^{1}) \in L^{2}(\Omega \times Y^{1})$, where $Y^{1} = [0, 1]$ such that

$$\lim_{\epsilon \to 0} \int_{\Omega} u_{\epsilon}(\mathbf{x}) \left(\phi(\mathbf{x}) h\left(\frac{x^{1}}{\epsilon}\right) \right) dx$$

$$= \int_{\Omega \times Y^{1}} u(\mathbf{x}, y^{1}) (\phi(\mathbf{x}) h(y^{1})) dx dy^{1}$$
(4)

for any $\phi \in C_0^{\infty}(\Omega)$ and any $h \in C_{per}^{\infty}(Y^1)$, then such a sequence u_{ϵ} is said to weakly two-scale converge to $u(\mathbf{x}, y^1)$. This convergence is denoted by $u_{\epsilon}(\mathbf{x}) - u(\mathbf{x}, y^1)$.

For vectors $\boldsymbol{u}_{\epsilon}$, equation (4) implies

$$\lim_{\epsilon \to 0} \int_{\Omega} \boldsymbol{u}_{\epsilon}(\boldsymbol{x}) \cdot \boldsymbol{\Phi}\left(\boldsymbol{x}, \frac{\boldsymbol{x}^{1}}{\epsilon}\right) d\boldsymbol{x}$$

$$= \int_{\Omega \times Y^{1}} \boldsymbol{u}(\boldsymbol{x}, y^{1}) \cdot \boldsymbol{\Phi}(\boldsymbol{x}, y^{1}) d\boldsymbol{x} dy^{1},$$
(5)

for every $\mathbf{\Phi} \in L^2(\Omega; C_{\text{per}}(Y^1))$, whose choice is explained in [9] (p. 8).

5. Strong two-scale convergence

The further extension of the class of test functions in Definition 4.1 leads to the basis of the following notion of the classical strong two-scale convergence [8, 10].

Definition 5.1. A bounded sequence $u_{\epsilon} \in L^{2}(\Omega)$ is called strongly two-scale convergent if there exists $u = u(\mathbf{x}, y^{1}) \in L^{2}(\Omega \times Y^{1})$ such that

$$\lim_{\epsilon \to 0} \int_{\Omega} u_{\epsilon}(\mathbf{x}) v_{\epsilon}(\mathbf{x}) dx$$

$$= \int_{\Omega \times Y^{1}} u(\mathbf{x}, y^{1}) v(\mathbf{x}, y^{1}) dx dy^{1}$$
(6)

for any bounded sequence $v_{\epsilon}(\mathbf{x}) \in L^{2}(\Omega)$ such that $v_{\epsilon}(\mathbf{x}) \rightarrow v(\mathbf{x}, y^{1}) \in L^{2}(\Omega)$. This convergence is denoted by $u_{\epsilon}(\mathbf{x}) \rightarrow u(\mathbf{x}, y^{1})$.

For vector (or matrix) $\boldsymbol{u}_{\varepsilon}$, equation (6) implies

$$\lim_{\epsilon \to 0} \int_{\Omega} \boldsymbol{u}_{\epsilon}(\boldsymbol{x}) \cdot \boldsymbol{v}_{\epsilon}(\boldsymbol{x}) \, d\boldsymbol{x}$$

=
$$\int_{\Omega \times Y^{1}} \boldsymbol{u}(\boldsymbol{x}, y^{1}) \cdot \boldsymbol{v}(\boldsymbol{x}, y^{1}) \, d\boldsymbol{x} \, dy^{1}.$$
 (7)

In the next well-known results, weak and strong two-scale convergence can be viewed as intermediate properties between the usual (onescale) weak and strong convergence.

Proposition 5.2. Let (u_{ϵ}) be a sequence in $L^{2}(\Omega)$ and $u \in L^{2}(\Omega \times Y^{1})$. Then,

(i)
$$u_{\epsilon} \to u \text{ in } L^2(\Omega) \Longrightarrow u_{\epsilon} \twoheadrightarrow u \text{ in } L^2(\Omega \times Y^1),$$

whenever u is independent of y^1 , the converse also holds,

(*ii*)
$$u_{\epsilon} \twoheadrightarrow in L^{2}(\Omega \times Y^{1}) \Longrightarrow u_{\epsilon} \twoheadrightarrow u \text{ in } L^{2}(\Omega \times Y^{1}),$$

(*iii*)
$$u_{\epsilon} \longrightarrow u \text{ in } L^2(\Omega \times Y^1) \implies u_{\epsilon} \longrightarrow \int_{Y^1} u(\cdot, y^1) \, dy^1 \text{ in } L^2(\Omega).$$

Proof. For (i), the proof is readily followed from Definition 4.1, the mean value property (3), and the property (d) of convergence in L^2 .

For (ii), it is obvious. Indeed, it suffices to take, in Definition 5.1,

$$v_{\epsilon}(\mathbf{x}) = \phi(\mathbf{x})h(\epsilon^{-1}x^{1}),$$

 $\phi \in C_0^{\infty}(\Omega), h \in L^2(Y^1)$, and recall (3), to derive (4) as desired. Moreover, from $u_{\varepsilon} \rightarrow u$ in $L^2(\Omega \times Y^1)$ (6), taking $v_{\varepsilon} = u_{\varepsilon}$, one obtains the relation

$$\lim_{\epsilon \to 0} \int_{\Omega} |u_{\epsilon}(\mathbf{x})|^2 d\mathbf{x} = \int_{\Omega \times Y^1} |u(\mathbf{x}, y^1)|^2 d\mathbf{x} dy^1.$$
(8)

For (iii), by the definition of weak two-scale convergence 4.1, it follows that

$$\lim_{\epsilon \to 0} \int_{\Omega} u_{\epsilon}(\mathbf{x}) \Phi\left(\mathbf{x}, \frac{x^{1}}{\epsilon}\right) dx$$

$$= \int_{\Omega \times Y^{1}} u(\mathbf{x}, y^{1}) \Phi(\mathbf{x}, y^{1}) dx dy^{1},$$
(9)

for every $\Phi \in L^2(\Omega; C_{per}(Y^1))$. Choosing $\Phi = 1$ in (9) and applying the property (c) of weak convergence, one obtains

$$u_{\epsilon}(\boldsymbol{x}) \rightharpoonup \int_{Y^1} u(\boldsymbol{x}, y^1) \, dy^1 = \langle u(\boldsymbol{x}, \cdot) \rangle \,, \qquad (10)$$

which implies that one can reach the usual weak limit from the two-scale limit by taking the average over the cell of periodicity. The converse of (ii) is also true as follows [8].

Lemma 5.3. Weak two-scale convergence $u_{\epsilon}(\mathbf{x}) \rightarrow u(\mathbf{x}, y^1)$ together with the relation (8) implies strong two-scale convergence $u_{\epsilon}(\mathbf{x}) \rightarrow u(\mathbf{x}, y^1)$.

Proof. The proof is based on [8]. Consider an arbitrary subsequence (still denoted by ϵ) $\epsilon \rightarrow 0$ such that there exist limits

$$\lim_{\epsilon \to 0} \int_{\Omega} u_{\epsilon}(\mathbf{x}) v_{\epsilon}(\mathbf{x}) \, dx = \alpha \,, \, \lim_{\epsilon \to 0} \int_{\Omega} |v_{\epsilon}(\mathbf{x})|^2 \, dx = \beta \,,$$

where $v_{\epsilon}(\mathbf{x}) \rightarrow v(\mathbf{x}, y^{1})$. Then, using the lower semicontinuity property [8] for $tv_{\epsilon} + u_{\epsilon}$, we obtain

$$\lim_{\varepsilon \to 0} \int_{\Omega} |t v_{\varepsilon}(\mathbf{x}) + u_{\varepsilon}(\mathbf{x})|^2 dx$$

$$\geq \int_{\Omega \times Y^1} |t v(\mathbf{x}, y^1) + u(\mathbf{x}, y^1)|^2 dx dy^1.$$

Applying (8), we get

$$t^{2}\beta + 2t\alpha \ge t^{2} \int_{\Omega \times Y^{1}} |v|^{2} dx dy^{1}$$
$$+ 2t \int_{\Omega \times Y^{1}} uv dx dy^{1}$$

Hence,

$$2t\left(\alpha - \int_{\Omega \times Y^{1}} uv \, dx \, dy^{1}\right)$$

$$\geq t^{2}\left(-\beta + \int_{\Omega \times Y^{1}} |v|^{2} \, dx \, dy^{1}\right)$$

On the right hand side of this inequality, we apply the lower semicontinuity property [8] again for v_{ϵ} . Then, with the arbitrariness of *t*, we must have

$$\alpha = \int_{\Omega \times Y^1} uv \, dx \, dy^1 \, ,$$

which is our desired result.

The following theorem is stated and proved in [8].

Theorem 5.4. Let $u_{\epsilon}(\mathbf{x}) \in L^{2}(\Omega)$, $u_{\epsilon}(\mathbf{x}) \twoheadrightarrow u(\mathbf{x}, y^{1})$. Suppose in addition that $u(\mathbf{x}, y^{1})$ is a Carathéodory function, $u(\mathbf{x}, y^{1}) \leq \Phi_{0}(y^{1})$, $\Phi_{0} \in L^{2}(Y^{1})$. Then,

$$\lim_{\epsilon \to 0} \int_{\Omega} |u_{\epsilon}(\mathbf{x}) - u(\mathbf{x}, \epsilon^{-1} x^{1})|^{2} dx = 0.$$
 (11)

References

- Mikhaila Cherdantsev, Kirillb Cherednichenko, and Stefan Neukamm. High contrast homogenisation in nonlinear elasticity under small loads. *Asymptotic Analysis*, 104(1-2), 2017.
- [2] Mustapha El Jarroudi. Homogenization of a nonlinear elastic fibre-reinforced composite: A second gradient nonlinear elastic material. *Journal of Mathematical Analysis and Applications*, 403(2):487 – 505, 2013.
- [3] Hervé Le Dret. An example of H¹-unboundedness of solutions to strongly elliptic systems of partial differential equations in a laminated geometry. *Proceedings of the Royal Society of Edinburgh*, 105(1), 1987.
- [4] S. Nekhlaoui, A. Qaiss, M.O. Bensalah, and A. Lekhder. A new technique of laminated composites homogenization. *Adv. Theor. Appl. Mech.*, 3:253–261, 2010.
- [5] A. El Omri, A. Fennan, F. Sidoroff, and A. Hihi. Elastic-plastic homogenization for layered compos-

ites. *European Journal of Mechanics - A/Solids*, 19(4):585 – 601, 2000.

- [6] G. A. Pavliotis and A. M. Stuart. Multiscale methods: Averaging and homogenization, volume 53 of Texts in Applied Mathematics. Springer-Verlag New York, 2008.
- [7] Giuseppe Geymonat, Stefan Müller, and Nicolas Triantafyllidis. Homogenization of nonlinearly elastic materials, microscopic bifurcation and macroscopic loss of rank-one convexity. *Archive for Rational Mechanics and Analysis*, 122(3):231–290, 1993. DOI: 10.1007/BF00380256.
- [8] V. V. Zhikov and G. A. Yosifian. Introduction to the theory of two-scale convergence. *Journal of Mathematical Sciences*, 197(3):325–357, Mar 2014.
- [9] Dag Lukkassen, Gabriel Nguetseng, and Peter Wall. Two-scale convergence. *International journal of pure and applied mathematics*, 2(1):35–86, 2002.
- [10] Dag Lukkassen and Peter Wall. Two-scale convergence with respect to measures and homogenization of monotone operators. *Journal of function spaces and applications*, 3(2):125–161, 2005.